Al for Computational Photography

Greg Slabaugh 5 Nov 2020

Note: This presentation contains a slide with flashing imagery.



What is computational photography?

Computational photography refers to image capture and processing using digital computation (instead of optical processes). It's a core topic in "low level" computer vision.









Denoising Inpainting Automatic white balance





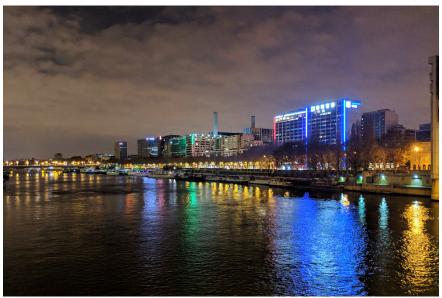
See in the dark



Super-resolution

Why is this interesting?





Sony a7R III Google Pixel 3

We're taking a lot of photos...

1.4 Trillion

photos will be taken in 2020

Proving the adage 'you'll never have fewer digital pictures than before', the number of photos taken worldwide is expected to grow again in 2020.



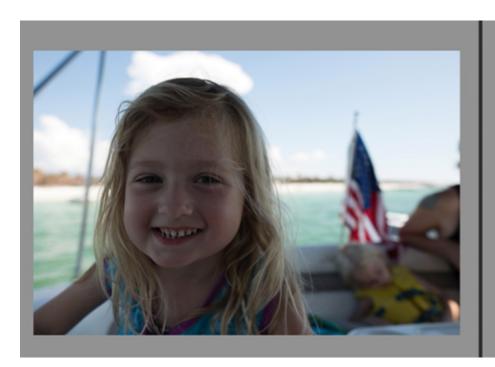
Compound Annual Growth Rate



...on our smartphones



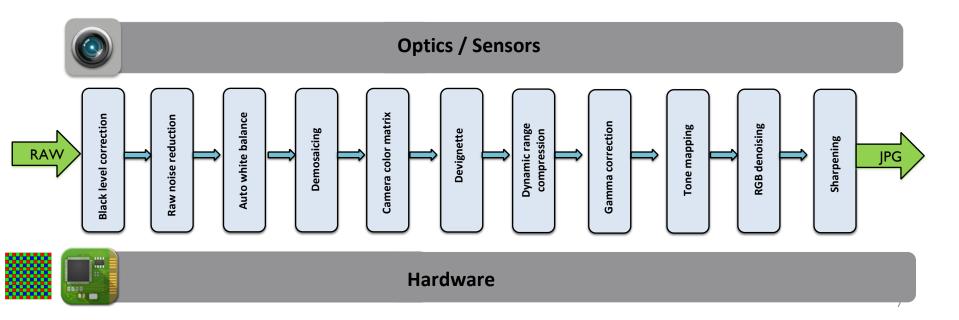
But how to get more out of our photos?





Traditional ISP pipeline

A traditional Image Signal Processor (ISP) is a pipeline of image processing algorithms to transform the raw data acquired by the image sensor into a high quality JPG image.



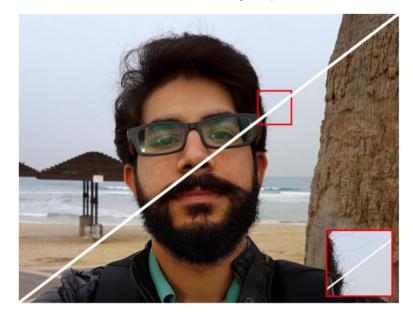
⇒ Can one use Deep Learning in the ISP?

⇒ Can one replace the ISP with a neural network?

DeepISP

DeepISP is a convolutional neural network that maps from RAW sensor data to a high quality RGB image.

- Low level network: denoising, demosaicing
- High level network: transforms colours using a quadratic function



<u>DeepISP: Toward Learning an End-to-End Image Processing Pipeline</u>, Eli Schwartz, Raja Giryes, Alex M. Bronstein, IEEE Transactions on Image Processing, 28(2), 2019.

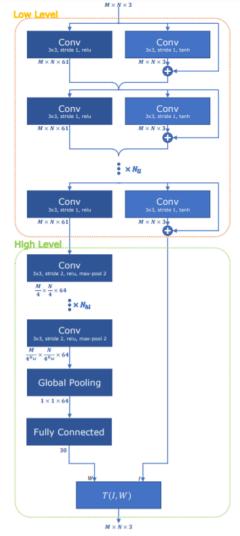
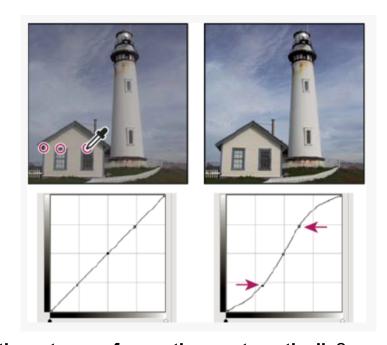


Image enhancement using curve layers

Photoshop / Lightroom allows users to adjust global image properties through the use of curves

Example: adjusting brightness



□ Can we build a neural network perform these types of operations automatically?

CURL

We recently introduced neural **CUR**ve **L**ayers (CURL) which learns and applies curve adjustments to an image. CURL has the following features:

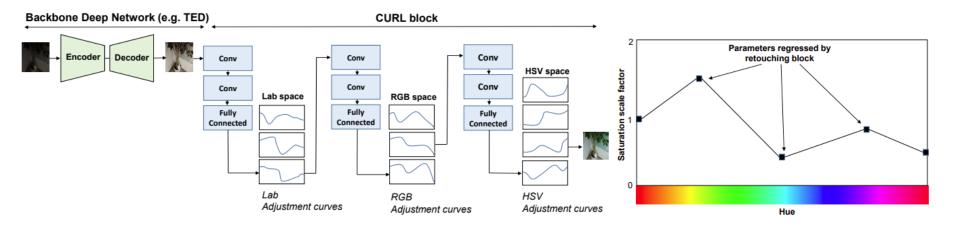
- Curves are piecewise linear
- Curves can flexibly adjust different image attributes (brightness, saturation, colour)
- Different colour spaces (RGB, HSV, LAB) supported
- Fully differentiable and trained end-to-end
- Predicted curves are intuitive and can be user adjusted
- State-of-the-art performance



1.0130

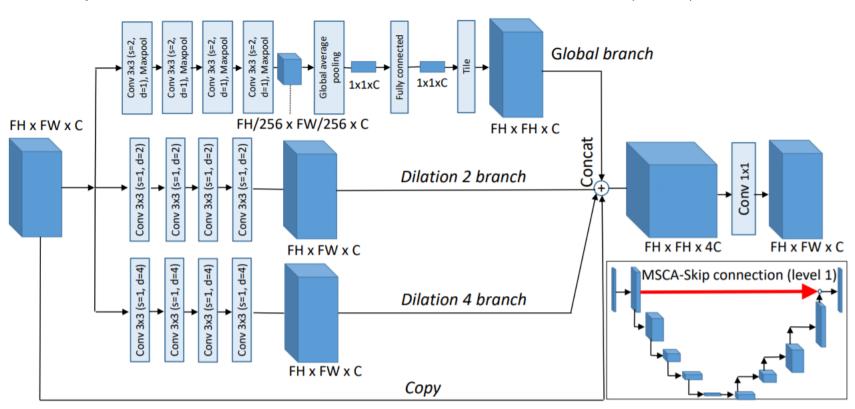
1.0125

CURL architecture



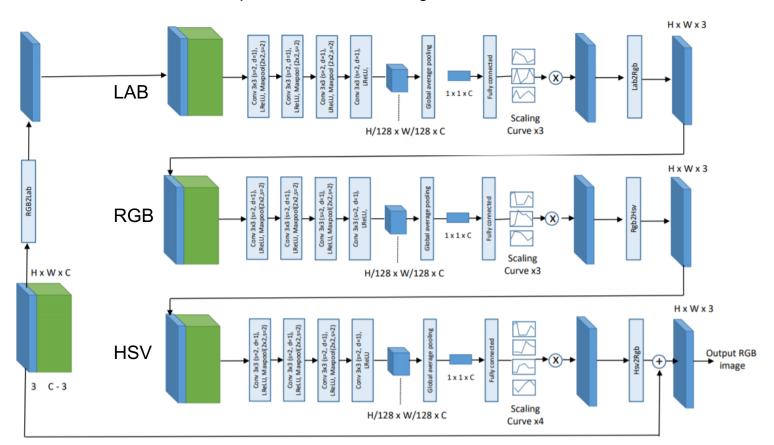
Transformed Encoder/Decoder (TED)

UNet style encoder/decoder but uses a multi-scale contextual awareness (MSCA) connection



CURL block

A CURL block is a multi-colour space neural retouching block that estimates enhancement curves



Loss and ablation studies

$$egin{aligned} \mathcal{L} = & \sum_{i=1}^{N} \mathcal{L}_{hsv}^{i} + \mathcal{L}_{lab}^{i} + \mathcal{L}_{rgb}^{i} + \mathcal{L}_{reg}^{i} \ & \mathcal{L}_{lab} + \mathcal{L}_{reg} \end{aligned}$$
 $egin{aligned} \mathcal{L}_{lab} + \mathcal{L}_{reg} \end{aligned}$
 $egin{aligned} \mathcal{L}_{lab} + \mathcal{L}_{hsv} + \mathcal{L}_{reg} \end{aligned}$

Loss is designed to control each of the colourspace specific transformations in CURL

 $\mathcal{L}_{lab} + \mathcal{L}_{reg}$ $\mathcal{L}_{lab} + \mathcal{L}_{hsv} + \mathcal{L}_{reg}$ All terms Groundtruth



Results

DeepISP (28.19 dB)

TED+CURL (29.37 dB)

Groundtruth



DeepUPE (16.85 dB)

TED+CURL (23.55 dB)

Groundtruth



Tables

Ordering	PSNR (test)↑
$HSV \rightarrow RGB \rightarrow LAB$	26.20
$RGB \rightarrow HSV \rightarrow LAB$	26.83
$LAB \rightarrow RGB \rightarrow HSV$	27.09
$LAB \rightarrow HSV \rightarrow RGB$	26.37
$RGB \rightarrow LAB \rightarrow HSV$	25.32
$HSV \rightarrow LAB \rightarrow RGB$	26.53

Architecture	PSNR ↑
TED+ CURL	27.04
TED	26.56
U-Net [13]	25.90
DeepISP [8]	26.51

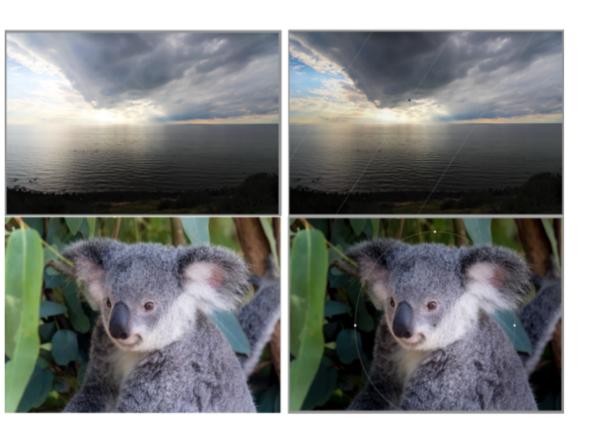
Architecture	PSNR ↑
TED+CURL	24.20
HDRNet [15]	21.96
DPE [3]	22.15
White-Box [2]	18.57
Distort-and-Recover [24]	20.97
DeepUPE [1]	23.04

Ordering through colour spaces

RAW to RGB

RGB to RGB

DeepLPF for local image enhancement



Graduated filters

Elliptical filters

Thank you